



OpenIMU300ZI

EZ-Family High-Performance IMU



The ACEINNA OpenIMU300ZI "EZ" is an easy-to-use high-performance 9-DOF open inertial platform. The OpenIMU300ZI features a precision 3-Axis Accelerometer, low-drift 3-Axis Rate Gyro, and 3-Axis Magnetometer. The low-power platform is powered by a 168MHz ARM M4 CPU with a Floating Point Unit. The OpenIMU300ZI runs the OpenIMU open-source stack that includes an optimized full-state Kalman Filter for Attitude and GPS-Aided Position-Velocity-Time (PVT) measurement. A free tool-chain based on VS Code supports PC, MAC, and Ubuntu.



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The ACEINNA OpenIMU300ZI is designed for use in embedded applications and operates from a 3.0 to 5.5 power supply. The cost-effective and light-weight cast aluminum housing provides rigidity and minimizes potential stress coupling from the PCBA to the sensor. Four mounting holes are provided to secure the OpenIMU300ZI to your PCBA with screws.

Applications

- Autonomous Vehicles
- Unmanned Vehicles
- Self-Driving Taxis / Delivery Vehicles
- Agriculture Vehicles and Implements
- Forklifts
- Robotics Control / Feedback
- Antenna / Camera Gimbaling and Stabilization



Features

- Easy to Customize Open Source Algorithms
- Precision 3-axis MEMS Accelerometer
- Low-Drift 3-axis MEMS Angular Rate Sensor
- High Performance 3-axis AMR Magnetometer
- 168 MHz ARM M4 processor
- SPI and up to 3 UART interfaces
- Open Source Tool Chain
- Open Source Algorithms (VG / AHRS / INS)
- Built in 16-State Open Source Extended Kalman Filter
- Open Community & Support
- Wide Temp Range, -40C to +85C
- High Reliability, MTBF > 50k hours

This product has been developed exclusively for commercial applications. It has not been tested for, and makes no representation or warranty as to conformance with, any military specifications or its suitability for any military application or end-use. Additionally, any use of this product for nuclear, chemical or biological weapons, or weapons research, or for any use in missiles, rockets, and/or UAV's of 300km or greater range, or any other activity prohibited by the Export Administration Regulations, is expressly prohibited without the written consent and without obtaining appropriate US export license(s) when required by US law. Diversion contrary to U.S. law is prohibited. Specifications are subject to change without notice.



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Performance Specification

Ta = 25°C, VDC = 3.3 V, unless otherwise stated

Angular Rate	MIN	TYP ²	MAX
Range (°/s)	-400		+400
Bias Instability (°/hr) ¹		6	
Bias Stability over Temp (°/s)		0.3	
Scale Factor Accuracy (%)		0.03	
Cross-Axis Error (%FSR)		0.02	
Angle Random Walk (°/√hr) ¹		0.3	
Configurable Bandwidth (Hz)	5		50
Acceleration	MIN	TYP ²	MAX
Range (g)	-8		+8
Bias Instability (μg) ¹		10	
Bias Stability over Temp (mg)		3	
Scale Factor Accuracy (%FSR)		0.03	
Non-Linearity (%FSR)		0.03	
VRW (m/s/√hr) ¹		0.06	
Configurable Bandwidth (Hz)	2		50
Magnetic Field	MIN	TYP ²	MAX
Range (mGauss)	-8000		+8000
Resolution (mGauss)		0.25	
Noise (mGauss/√Hz)		0.25	
Bandwidth (Hz)		5	

Note 1: Allan variance curve, constant temperature

Note 2: Typical values are 1-sigma values unless otherwise noted

Electrical Specifications

Characteristic	Specification
Input voltage	3.0 – 5.5 V
Power Consumption	< 350 mW
Interface	SPI and UART
Max Output Data Rate - SPI	200 Hz
Max Output Data Rate - UART	200 Hz
Input Clock Sync	1pps, 1 kHz

Physical Specifications

Characteristic	Specification
Size	24.15 x 37.7 x 9.5 mm
Weight	<17 gram
Connector	20-Pin (10x2) 1.0 mm pitch header
Mating Connector	SAMTEC CLM-110-02
Mounting holes	4 x 2.5 mm thru hole

Environmental Specifications

Characteristic	Specification
Operating Temperature	-40 °C to 85 °C
Storage Temperature	-55 °C to 105 °C

ESD Specification

Model	Class	MAX
Human Body	2	2000 V
Charged Device	II	500 V

Qualification Summary (Not inclusive of all tests)

Item	Condition	Summary	
Hot Soak - Operating	Powered	96 Hours 85 °C per IEC 60068-2-2, method BE	
Cold Soak - Operating	Powered	96 Hours -40 °C per IEC 60068-2-1, method AD	
Temperature Cycle	Not Powered	415 cycles, -40 °C to 85 °C	
Temperature Cycle	Powered	141 cycles, , -40 °C to 85 °C	
Temperature Shock	Not Powered	50 Cycles; -40 °C to 85 °C, <60 s transition, 1 hour dwell	
Mechanical Shock	Powered	3 Shocks x 3 axis x 2 directions (18 total) 500 m/s ² , ½ sine, 11 ms pulse	
Vibration Swept Sine	Powered	5 to 2000 Hz; 5 to 55 Hz Disp. = 0.01 in; 55 Hz to 2000 Hz, 1.5 g Peak	
Vibration Random	Powered	Frequency Breakpoint	Acceleration Spectral Density (g ² /Hz)
		5	0.015
		100	0.04
		1000	0.04
		2000	0.02